

Modeling the Human Operator's Cognitive Process to Enable Assistant System Decisions

Ruben Strenzke (presenter) & Axel Schulte

Universität der Bundeswehr München Faculty of Aerospace Sciences Institute of Flight Systems (IFS)

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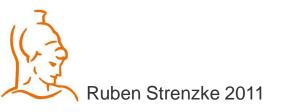


Manned-Unmanned Teaming (MUM-T)



- Assistant System Approaches for MUM-T
 - Assistant System Requirements
 - Recognizing the Operator's Current Activity
 - Evaluating the Operator's Plan

Human Operator Model



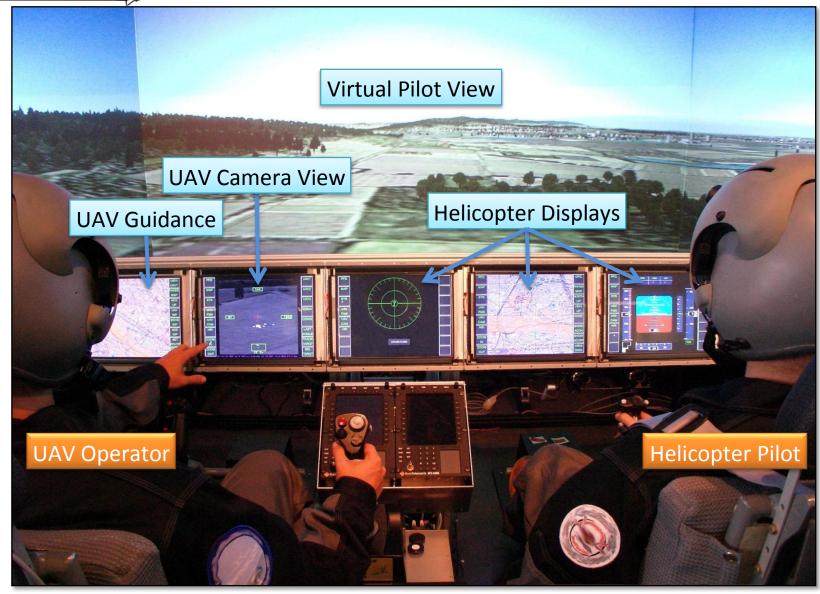
Manned-Unmanned Teaming (MUM-T) Crew Concept



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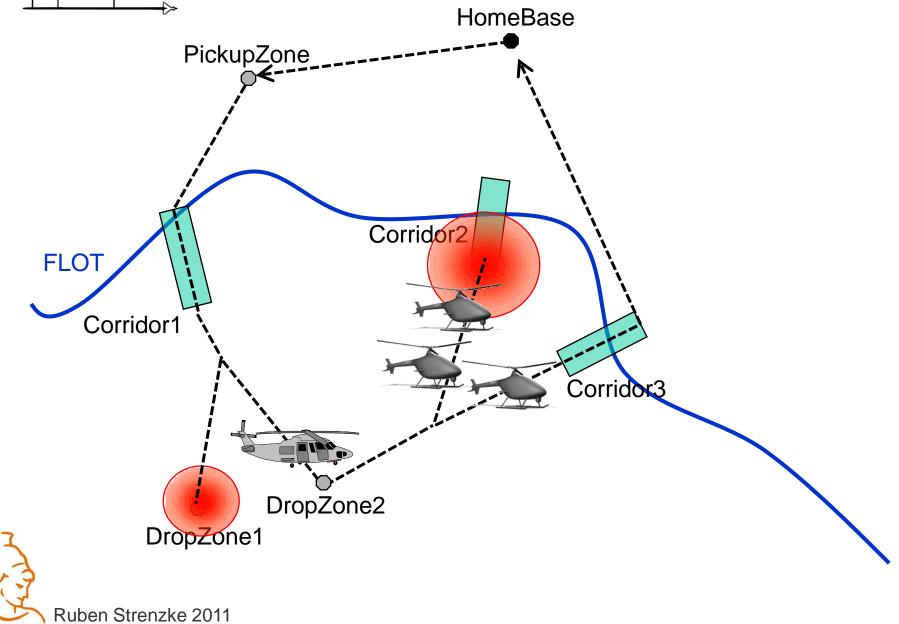
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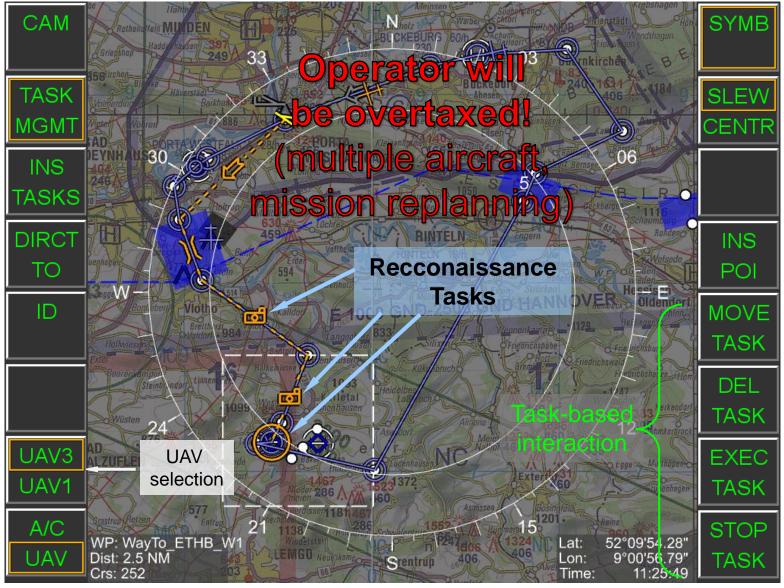


MUM-T Troop Transport Mission





Multi-Aircraft Guidance: Human-Machine Interface



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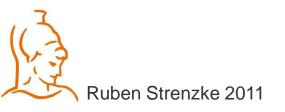
Manned-Unmanned Teaming (MUM-T)



Assistant System Approaches for MUM-T

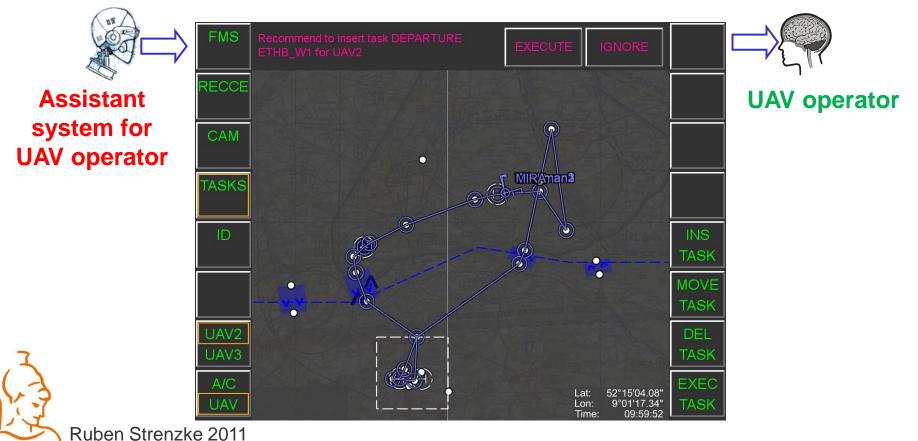
- Assistant System Requirements
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- Assistant system shall guide attention to most urgent task
 and intervene if necessary
- Assistant system communicates via
 speech synthesis monolog and display dialog
- Three initiative levels: advice \rightarrow proposal generation \rightarrow task re-allocation



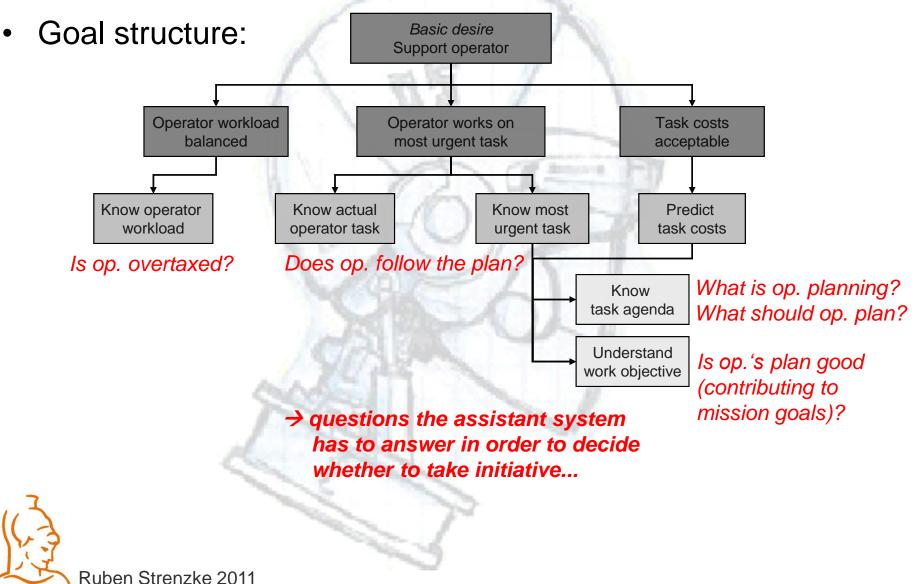


- Assistant System takes initiative: "UAV1 needs follow-up task"
- Operator presses proposal-button
- Assistant System proposes: "add task transit A B for UAV1"
- Operator presses accept-button
- Assistant System affirms: "added task transit A B for UAV1"
- etc.





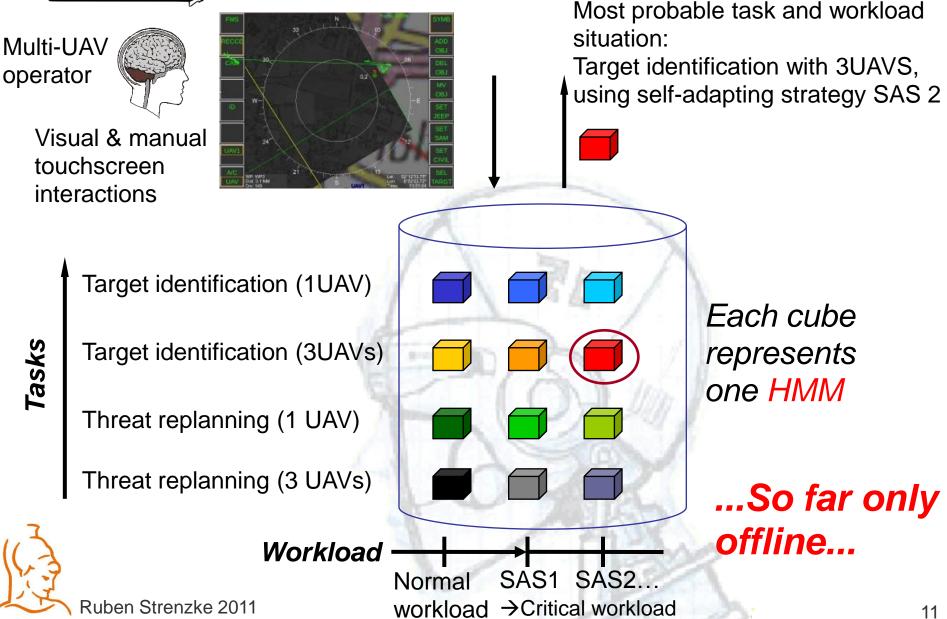
Knowledge-Based, Goal-Driven Assistant System





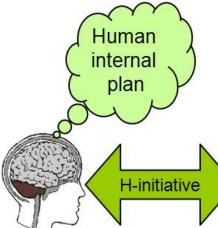
Tasks

Estimating Operator's Current Workload and Task





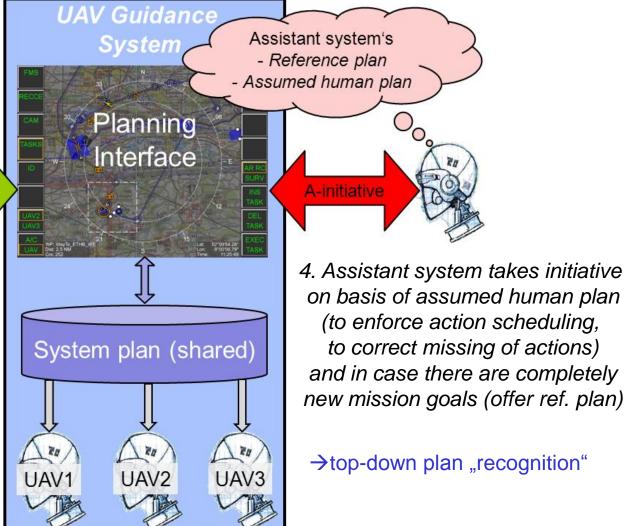
Mixed-Initiative Mission Planning



1. System plan is entered incrementally → partial human plan

2. Assistant System has direct access to system plan

3. Assumed human plan is the best known completion of the system plan (LPG in incremental mode)



→Srivastava et al. (2007) generating diverse plans via local search (LPG-d)
 →Nguyen et al. (2009) working with partial user *preference* models
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- Estimating operator's current mental resource utilization / capacity (online)
 - to adapt information channel used by assistant system
 - precondition: we have to know about operator's current
 - task situation (to match with a task-resource model)
 - activity (e.g. radio transmission, looking at display x)
- Improving gaze tracking data quality for online decision-making
 - data about operator's situation awareness (beliefs)
 - \rightarrow which map object looked at, which message read
 - precondition: know about operator's task situation
 - → Kalman Filtering

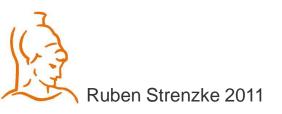


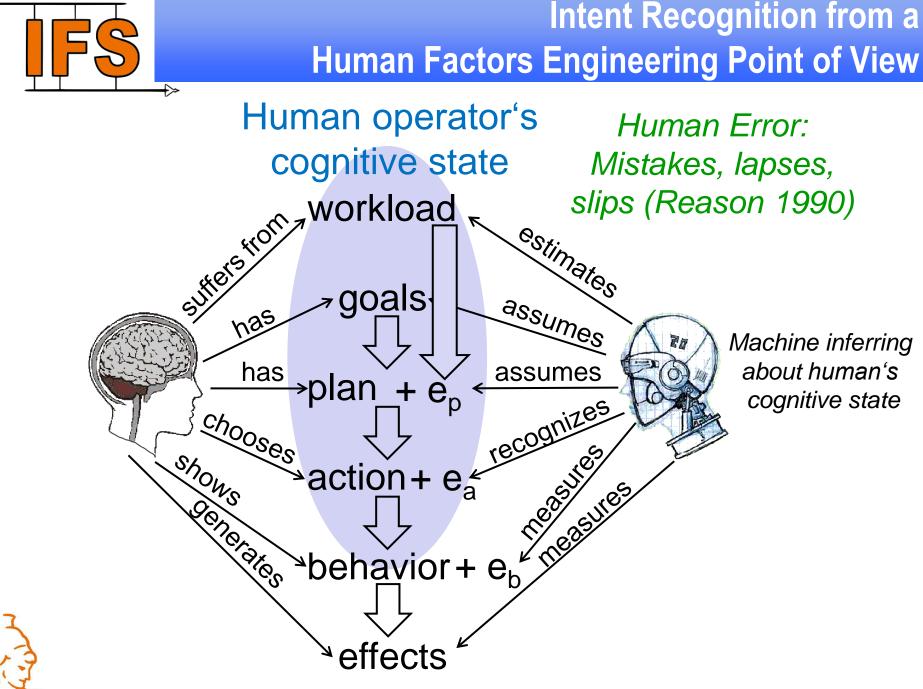


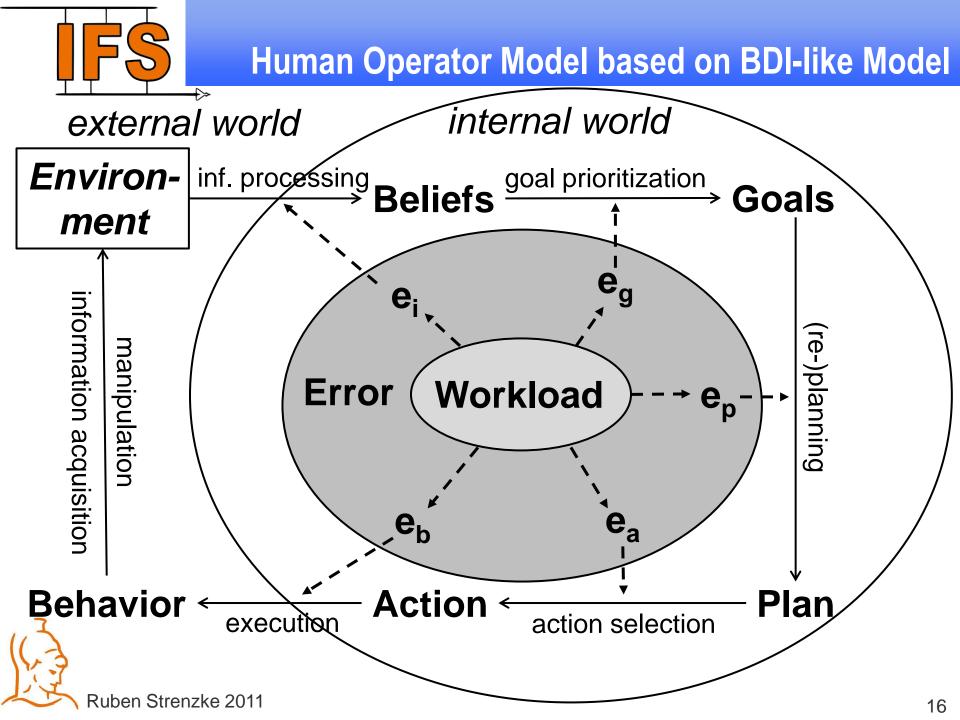
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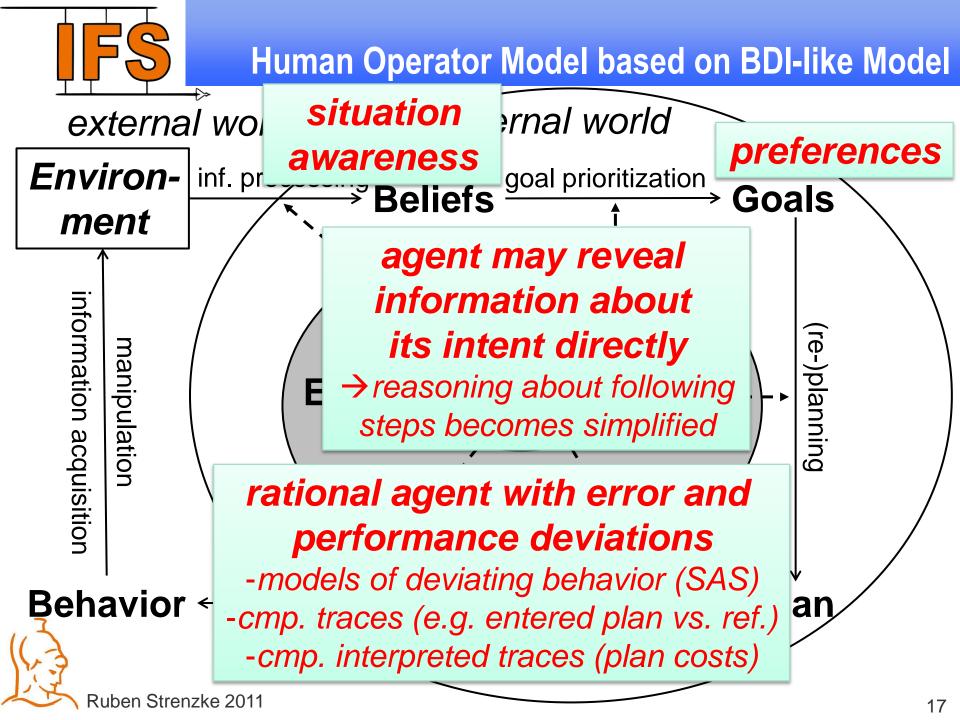
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Thank you very much for your attention!

Comments and questions welcome...

ruben.strenzke@unibw.de